

AUTOMATIC BAR FEEDER

ATTACHMENTS LIST

MANUAL FOR USE AND MAINTENANCE

KEYBOARD INSTRUCTION MANUAL

SPARE PARTS BOOK

SCHEMATICS

EC CONFORMITY DECLARATION FOR MACHINE

KID 80 - IV Touch					
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1 - BASIC INFORMATION



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Iemca reserves the right to make changes to the products described herein at any time.

Thus, this document may not not exactly match the product.

The data contained herein relate to a product range and are not specific to the serial number appearing on the cover.

1 - BASIC INFORMATION



1.1 Control description



INFORMATION:

From the touch keyboard you can start the bar feeder in Automatic mode, even when the lathe "MAN/AUT" signal is in Manual mode.

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INFORMATION:

When the bar feeder is in Automatic mode, the bar feeding is possible only when the Lathe "MAN/AUT" signal is in Automatic mode.

INFORMATION:

By pressing the Manual mode button on the touch keyboard, you can prevent the lathe from starting the bar feeder in Automatic mode.



EN 1 - BASIC INFORMATION

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The figure represents the control position on board the machine.



- 1 TOUCH-SCREEN: display and main controls
- 2 MAIN SWITCH: turns the power supply on and off.
 - Position 0 (OFF) the machine is not powered.
 - Position I (ON) the machine is powered.
- 3 EMERGENCY STOP PUSH-BUTTON: stops the bar feeder in case of emergency. For restart release the push-button manually.

1 - BASIC INFORMATION



Keyboard control description



- 1 Function access, bar loading and new set-up (guide channel and bar pusher replacement) button.
- 2 Programme save or recovery management access button.
- 3 Selects the "Operator Parameters" mode.
- 4 Selects the "Iemca Parameters" mode.
- 5 Error reset button: to restart the bar feeder after the stop caused by an error, press the button and hold it down until the bar feeder is started.
- 6 Bar feeder stop button (red light): press this button to stop the bar feeder and reset the "Errors".
- 7 Selects the semi-automatic mode.Press to select, press again to deselect.
- 8 Activates the "step by step" operating cycle: every time the button is pressed, one step is performed.
- 9 Selects the manual mode.
- 10 Selects the automatic mode.
- 11 It resets the "BAR FEEDER ZERO SETTING" of the carriage. Press the 0-AXIS button and release it when the carriage starts moving towards the "BAR FEEDER ZERO SETTING" position.
- 12 Remnant detection disabling button Press the button to feed a "new" bar without the detection of bar remnant in the bar pusher collet.
- 13 Allows to return to the main menu display.
- 14 Moves the bar pusher at a low speed
- 15 Moves the bar pusher at high speed.
- 16 Displays the software and the push-button panel identification data.



EN 1 - BASIC INFORMATION



- 17 In the bar showed, warnings received from the bar feeder during machining procedures are displayed. Their function is to guide the operator for correct operation of the machine. In detail, the possible warnings are the following ones:
 - K1: It is displayed at the right-hand side of the bar when the bar feeder is in the bar end position. It will not be displayed under any other operating conditions.
 - FEEDING STOP
 - DOOR SAFETY
 - SAFETIES FROM LATHE
 - BAR FEEDER ZERO SETTING MISSING
 - MANUAL | AUTOMATIC SIGNAL FROM LATHE
 - BAR PUSHER NOT IN POSITION!
 - MOVE CARRIAGE TO BACK LIMIT STOP.
 - CARRIAGE BACK
 - AUTOMATIC MODE
 - MANUAL MODE
 - AUTOMATIC OR MANUAL MODE?
 - SEMI-AUTOMATIC MODE
 - CARRY OUT BAR FEEDER ZERO SETTING: the machine requires a zero setting as a reference (see manual controls).
 - RESET WITH BUTTON: the machine is in alarm mode and requires zero setting by pressing I (reset)





18 The bar shows the bar feeder phase during machining, in detail:

- Bar feeder in stand-by
- Bar pusher return
- Zero axis
- Bar loading
- Bar first feeding
- Return after first feeding
- Facing phase
- Open collet
- 19 Displays the total number of machined pieces.
- 20 Graphic animation: it shows the feeding carriage and the bar pusher position (raised or lowered) with respect to the bar feeder axis, in run-time mode.
- 21 Position from "0": it stands for the feeding carriage position with respect to the S1015 zero axis sensor; Position from "F": it stands for the feeding carriage position with respect to the maximum feeding position of the bar feeder.
- 22 Allows to enter a new menu that includes other keys.
- 23 Displays the number of machinable pieces.
- 24 It displays the bar feeder phase during machining procedures.



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2.1 AUTOMATIC CYCLE START

- 1. Power on the lathe.
- 2. Power on the bar feeder, by turning the main switch to position I (ON)
- 3. Start the bar feeder:
- 4. Select the manual mode:

5. Select the "BAR FEEDER ZERO SETTING" of the carriage:

- 6. Bring the bar fore end close to the cutting tool:
- 7 Start the closing of the lathe collet and start working by selecting the automatic mode:

2 - INFORMATION FOR USE



2.2 OFFSET PROCEDURE (ADJUSTMENT)

Foreword

This procedure must be performed to optimize the bar feeder axis movements. This procedure should be performed occasionally (once a month is recommended) to compensate any wear of the mechanical feeding units that could alter the AXIS control operations.



INFORMATION:

Before performing the following procedure make sure that the mechanical parts have no clearances and that the zero axis sensor is positioned correctly (it shall not to be too retracted).

For the offset procedure perform the following operations in the given order:

- 1 Set the machine to manual mode
- 2 Carry out the bar feeder zero setting
- 3 Bring the bar pusher carriage to the centre of the bar feeder << >>
- 4 Provide the enabling signal for operations keeping the zero position sensor active using a security block or screwdriver and check that the axis moves.
- If the axis does not move, go straight to point 6; if it moves, adjust the value of the machine parameter no.70, under the item "Ax. Offset Compensat." in accordance with the "displacement" movement that the axis is carrying out; if the axis moves forward decrease the set value and if the axis moves towards zero, increase the set value. When the axis is still and stays in position for at least 20 seconds, the value set can be considered correct.
- 6 Carry out an absolute movement (e.g.: the first movement in step by step) and make sure, through the operator panel (OP), that the axis is positioned with a maximum error of +/- 0.1 mm; make sure also that the position does not undergo variations.



KID 80 SIV

2.3 **CYCLE PERFORMING MODE IN THE STEP-BY-STEP FUNCTION**

Foreword

This mode may be used for many reasons, as for instance:

- to open the guide channels; •
- to check a complete bar change cycle;
- to check the bar feeder mechanics;
- to load a single bar so as to check the facing; •
- etc. •

Procedure

- 1. press **RESET** to start the bar feeder;
- check that the guide channels of the bar feeder are closed. If not, close the guide channels in manual mode.
- 2. press and then to select the semiautomatic mode;

STEP B

- 3. press step, the bar feeder performs the first step (bar pusher return);
- SIMATIC HMI MANUAL MODE F <<<< Pos. da 0 Pos. da F C. 55 % << +102,450 +1490,575 🗲 ІЕМСА >> SEMI STEP BY AUT 0-ASSE

SIEMENS

press step, the bar feeder performs the second step, and so on. 4



2.4 BAR FEEDER STOP

Bar feeder stop in emergency.

1. Press the emergency button to stop the bar feeder.



If the emergency stop is activated whilst the lathe is working, before restarting the working cycle, check that no dangerous conditions have been created due to the sudden stop. For example: if the tool was removing chips, move the tool away from the work piece before restarting the lathe.

Stopping the bar feeder at the end of the machining cycle.

WARNING - CAUTION

When stopping the machine normally, do not use the emergency buttons.

- 1. Complete the operations of your working schedule.
- 2. Stop the bar feeder:
- 3. Stop the lathe.
- 4. Turn off the electrical supply of the bar feeder by turning the main switch to the 0 (OFF) position.



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2.5 0-AXIS PROCEDURE (MANUAL MODE)

List of causes requiring the 0-Axis in manual mode:

- carrying out the manual 0-Axis periodically is recommended;
- if the bar pusher axis is moved by means of the crank or the lathe headstock is moved with the bar feeder powered off (no power supply).
- if the feeding chain is tightened (by means of the mechanical chain tightener, see Operation and Maintenance Manual, "Feeding chain - Adjustment").

2 - INFORMATION FOR USE

Set to manual mode

2.5.1 BAR LOADING CYCLE - FACING PROCEDURE

The following procedure describes the feeding of a new bar until the facing position is reached:

then press the *formula* key that allows to enter the guick bar loading function to the facing position.

MAN



The bar feeder starts the bar loading cycle, which stops when the new bar is positioned. The loading cycle of the new bar takes into account parameter 3 (facing mode) and parameter 2 (facing position).

If the operator releases the key, the cycle goes on until it is completed.

INFORMATION:

Without the open collet signal from lathe, the bar feeder carries out the above mentioned procedure, but the bar stops before entering the lathe collet (waiting for the open collet signal). With the open collet signal from lathe, the bar is loaded and positioned past the lathe collet according to parameters 2 and 3.

WARNING - CAUTION:

Check that the bar to be loaded in the magazine is present.









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2.6 OPERATOR PARAMETERS: OPERATION MODE

These parameters are needed for the bar feeder automatic cycle programming and should be set according to the working requirements as well as to the lathe type that is connected to the bar feeder. Some parameters concern the working phase, while others are used for the bar change phase.



WARNING - CAUTION

The parameters are set to a default value (preset value): the bar feeder performs the automatic cycle according to these values. Some parameters may not be appropriate for the lathe type or the type of machining requested.

The main operation modes are listed hereunder:

- Accessing the parameters
- Parameter display
- Parameter modification
- Subparameter display
- Subparameter modification
- Exiting the parameters

2 - INFORMATION FOR USE



2.7 PARAMETER ACCESSING AND DISPLAY



2. Enter "Main Menu" mode:

KID 80 SIV

2.7.1 HOW TO ACCESS AND DISPLAY IEMCA PARAMETERS



1. When the bar feeder is switched on the main screen appears:

Select "OPERATOR PARAMETERS"

3. Select the "Select Parameter List" button



SIEMENS SIMATIC HM

OPERATOR Parameters
Selection

SELECT by SUBJECT
SELECT the NUMBER
BROWSE the LIST





Press the "SELECT PARAMETER NUMBER" button to access the desired parameter immediately (see step 6).

To select the desired parameter, proceed as follows:

- 5. Enter "OPERATOR Parameters" mode Press "PARAMETER NUMBER"
- 6. "OPERATOR Parameters Selection" screen will be displayed on the screen, press:

7. Enter the parameter number, for example "1"; the

parameter value changes from 0 to 1; confirm:

8. To return to the short Menu press and proceed as described in Section 2.6.1.



IEMCA Parameters Selection Enter Parameter No. (0.100) and carry on...

SIMATIC HMI

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4. Press the buttons: **I** or **I** all the other parameters will appear in sequence.



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2.7.2 ACCESSING AND DISPLAYING SUBJECT MENU PARAMETERS

1. When the bar feeder is switched on, the entry screen is displayed: Select "Specialized Operators":



2. Enter "Main Menu" mode: Select "OPERATOR PARAMETERS".

3. Select the "Select parameter subjects" button









4. "OPERATOR Parameters Selection" screen will be displayed

SIEMENS	SIMATIC HM
OPERATOR Pa Select	rameters ion
FEEDING	
FEEDING	
CHECKS	÷
SETTINGS	
PULSES	P
INTERFACE	
FACING	
	I
SwTP	

5. Select the desired subject from the drop down list.



- 6. Press the buttons: **I** to access the parameters of the desired subject.
- 7. To return to the home page press and proceed as described in Section 2.6.1.





KID 80 SIV

2.8 PARAMETER MODIFICATION

- The desired parameter should be displayed:
 "Parameter screen example"
- 2. Select the parameter value:

Selected value: 100 (mm)

- SIEMENS SIMATIC HMI no. 1 Bar end adjustment Bar end 0 (K1A) Bar end 0 (K1B)
- 3. Enter the value to be assigned, for example "300",and confirm:

SIEMENS SIMATIC HMI										
*	* 300									
q	w	e	r	t	У	u	i	0	р	J
а	s	d	f	g	h	j	k	Τ	+	
₽	z	x	с	v	b	n	m	쇼		
Esc	Del	.123				Help	-	-	◀	

SIEMENS SIMATIC HMI no. 1 Bar end adjustment Bar end 0 (K1A) Bar end 0 (K1B) (K1B)

the value changes from 100 to 300

2 - INFORMATION FOR USE

4. At this stage the value is no longer blinking. If the value is not confirmed when entered, the last value will reappear.

SIEMENS	SIMATIC HMI					
no. 1 Bar end adju	stment	T				
Bar end	100					
Bar end (K1A)	0					
Bar end (K1B)	0					

KID 80 SIV

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2.9 EXITING THE PARAMETERS

1. Exit the "parameter display" mode:



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2.10 PROGRAMME ARCHIVE ON SD MEMORY

"Programmes" Download/Save mode makes it possible to download into the bar feeder PLC the complete setting programmes coming from the SD card connected to the Touch keyboard. Also an already existing programme can be directly saved from the PLC into the SD card.

DOWNLOAD A PROGRAMME FROM USB TO PLC

1. Press the manual key , then stop with stop to enter the Main Menu screen



Press the 🔲 key, the display will show "PROGRAMMES"

3. Press the

number.

 Press "Programmes"; screen "choose programme" from 1 to 500 will be displayed

key to select the desired programme





5. Press "Yes" to continue the download procedure; otherwise, press "No".

4. Press the \frown or the \frown key to enter the

desired programme number. Press the 🛄 key

6. The "Data writing in progress" procedure is displayed for a few seconds.

- 7. When the procedure is complete the display shows: "Data writing completed".
- ata writing completed".

 SIEMENS
 SIMATIC HMI

 Download
 Programme name:

 Boss 21 N
 Programme No.:

 Om
 Om

 Data writing completed
 Om

EXIT











KID 80 SIV

8. Press "Exit" EXIT to return to the home screen, the display will show: "Main Menu".



PROGRAMMES

Programme name: Boss 21 N

Programme No.(1..100):

001

SIMATIC HMI

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2 T

SAVE A PROGRAMME FROM PLC TO USB

Repeat the procedure explained up to step 4 in the "DOWNLOAD FROM USB TO PLC" instructions.

- 1. Press the or the key to enter the desired programme number. Press the Save key.
- 2. Enter the name that will identify the stored programmed.



3. Press "Yes" to continue the download procedure; otherwise, press "No". The home screen "PROGRAMMES" will be displayed.



- INFORMATION FOR USE

2

5.

key to continue.

4. The "Data reading in progress" procedure is displayed for a few seconds.

A screen is displayed that asks to press the

 When the procedure is complete the display shows: "Data save completed", press

- 8. When the procedure is complete the display shows: "Data save completed", press EXIT
 - SIEMENS SIMATIC HMI Download Programme name: Boss 21 N Programme No.: COM Data save completed Backap Ok EXIT











KID 80 SIV

SIMATIC HMI

2.11 OPERATOR PARAMETERS: DESCRIPTION

no. 1 Bar end adjustment

Defines the position where the bar feeder should send the "bar end" signal to the lathe. This value is referred to point (F) (maximum bar pusher feeding point), and corresponds to the piece length plus the cutting tool thickness.

Parameter: A - Bar end adjustment

Subparameters:

- B Bar end K1A adjustment
- C Bar end K1B adjustment





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The "Bar end 1 adjustment" subparameter can be used for three separate functions.

- the subparameter sends an interface signal to the bar feeder-lathe (2nd Bar end);
 the subparameter allows opening the additional bush;
- 3) The subparameter sends an interface signal to the bar feeder-lathe (prevents the headstock from completing the return stroke).



INFORMATION:

Using the "Bar End 1 Adjustment" subparameter rules out the possibility for one of the the above mentioned functions of being used simultaneously with the other

1) the subparameter sends an interface signal to the bar feeder-lathe

Defines the position where the bar feeder should send the Bar End Signal 1 to the lathe.



This value refers to point (F) (maximum bar pusher feeding point), and is a higher length than value (A).

The lathe enters a subprogram corresponding to a new machining cycle, where the length of the piece to be machined is shorter than the one of the main program.

INFORMATION:

If the Bar End Adjustment subparameter 1 is used, the bar end adjustment value should be set according to the length of the piece in the 2nd working cycle.

2) the subparameter allows opening the additional bush Procedure for setting the "Bar End 1 Adjustment" subparameter for the additional bush opening

a) Additional bush opening synchronized with the length of the machined piece

- Move the lathe headstock "K" in its completely forwards limit stop position;
- move the bar pusher "S" forwards without the bar inside the guide channel positioning the front part at about 30 mm from the additional bush "L";
- Check the value relative to the position "F" on the display (which by definition is called "PdF1")
- the measured value shall be added to the value set in the "Bar End Adjustment" parameter and inserted in "Bar End 1 Adjustment" parameter



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KID 80 SIV



b) Additional bush opening at a fixed value

- Move the lathe headstock "K1" in its completely back limit stop position;
- move the bar pusher "S" forwards without the bar inside the guide channel positioning the front part at about 30 mm from the additional bush "L";
- Check the value relative to the position "F" on the display (which by definition is called "PdF1")



 the measured value shall be added to the value set in the "Bar End 1 Adjustment" subparameter





INFORMATION:

The additional bush accessory on the lathe is installed if applicable from the lathe-bar feeder mechanical interface or upon customer's request.

3) The subparameter sends an interface signal to the bar feeder-lathe (prevents the headstock from completing the return stroke).

There is a condition in which the length of the loaded bar plus the length of the bar pusher added to the max headstock stroke is greater than the distance between the 0-axis sensor and the lathe collet. If the headstock moves back with closed collet, the bar and the bar pusher may exceed the maximum stroke allowed (causing a mechanical collision or a bar deformation).

If a value greater than or equal to 1500 mm (value is referred to point F) is set in the subparameter (B), its function becomes that of "headstock overrun safety".

Π

INFORMATION:

warning: with a value lower than 1500mm, subparameter "B" remains available for functions 1) and 2).



INFORMATION:

Warning: during the bar change cycle, the signal is disabled.
KID 80 SIV

no. 2 Facing length

Defines the movement of the bar fore end according to point (C) (facing point). Both positive and negative values.

- B Parameter 2 (positive value)
- D Parameter 2 (negative value)



no. 3 Facing mode

Defines the facing operation.

0 - (TO THE LIMIT STOP); once the bar has exceeded the value defined in parameter 2, it proceeds until the bar limit stop or until the tool.

1 - (IN POSITION); the bar is positioned in the point defined in parameter 2.





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KID 80 SIV

Subparameters:

- B Overrun admitted after (CHK with 0 mm is excluded)
- C Facing to limit stop (Vmax)
- D Facing to limit stop (Cmax)



	DEFAULT VALUE	PROGRAMMABLE VALUE		
	Kid 80	Kid 80		
A	to the limit stop	to the limit stop/in position		
в	0	0		
С	10	/		
D	35	/		

KID 80 SIV

FML

EN

no. 4 Short feeding safety

During every feeding stage, it checks that the bar does not go further than the value set in parameter 6 and keeps the tolerance level set in parameter 4. Should this not occur for any reason, when the lathe cuts the "FEEDING" signal, the bar feeder goes into "ALARM". If parameter 6 is set to 0, this parameter is not active.

- A Parameter 4
- B Parameter 6





- 0 (Not enabled for first piece); the parameter is active for all feeding operations except for the first piece.
- 1 (Enabled for first piece): the parameter is active for every feeding operation (the facing phase excepted).

INFORMATION

The short piece control cannot be performed in sliding headstock lathes (bar feeding is carried out by the headstock).

i

INFORMATION:

Setting the subparameter to 1 (Enabled for first piece), the "short piece" (parameter 4) checks are activated straight after the first piece.



KID 80 SIV

no. 5 Long feeding safety

During every feeding stage, it checks that the bar does not go further than the value set in parameter 6 added to the value set in parameter 5. Should this not occur for any reason, the bar feeder goes into "ALARM".

If parameter 6 is set to 0, this parameter is not active.

C - Parameter 5

D - Parameter 6





DEFAULT VALUE	PROGRAMMABLE VALUE		
Kid 80	Kid 80		
0	/		

- 0 (Not enabled for first piece); the parameter is active for all feeding operations except for the first piece.
- 1 (Enabled for first piece): the parameter is active for every feeding operation (the facing phase excepted).

М

INFORMATION

In the sliding headstock lathe, you can use this parameter to check for any tool breakages; enter a value of a few millimetres (maximum 5 mm).

INFORMATION:

Setting the subparameter to 1 (Enabled for first piece), the "short piece" (parameter 4) checks are activated straight after the first piece.

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no.6 Piece length

Defines the feeding value at each collet opening.

This parameter is active only if parameter 35 is set to "1" or "2".

When parameter 35 is set to "0", this parameter is not active.

A parameter 6







DEFAULT VALUE	PROGRAMMABLE VALUE		
Kid 80	Kid 80		
0	/		

no. 7 Open collet speed

Defines the "FEEDING" speed value.





KID 80 SIV

no. 9 Open collet thrust delay

At the "FEEDING" signal from the lathe, the bar pusher delays the feeding in accordance to the set time.

Application example: it should be used when the mechanical movement of the collet opening is slow (double-cone collet).



DEFAULT VALUE	PROGRAMMABLE VALUE
Kid 80	Kid 80
0	/

no. 10 Closed collet thrust delay

At the "closed collet" signal from the lathe, the bar pusher continues pushing in accordance to the set time.

Application example: it should be used when the mechanical movement of the collet closing is slow (double-cone collet).



1

0



no. 11 Collet entry slowdown

Defines the length of the slowdown section from (F) to (G). Along this section the bar moves at the collet entry speed (see parameter 12).



F = collet entry slowdown start referred to (C); G = see subparameter (N) of Parameter 14; C = Collet outer alignment Parameter 64; I = Facing (Parameter 64 + Parameter 2), in the example in the picture the hypothetical value entered in Parameter 2 = 100 mm. The value can be either positive or negative, for further information see Parameter 2.





KID 80 SIV

no. 12 Collet entry speed

Defines the value by which the speed is reduced in the slowdown section (see parameter 11 "A").



FIEMCA *KID 80 SIV* EN

no. 13 Collet entry torque

Defines the thrust value that the bar receives during its feeding in the lathe collet.

It is active in the slowdown section (see parameter 11).





KID 80 SIV

SIMATIC HMI

with closed collet

/

+400.000 mm

+20.000 mm

no. 14 Pulse number

Defines the number of pulses that the bar receives so as to simplify its feeding into the lathe collet. It is active in any point inside the "pulse window". Description of the phase order:

- the bar enters the pulse phase;
- the bar meets the obstacle (the collet); the pulses start;
- the bar exits the pulse phase.

Subparameters for setting the pulse window:

- M Pulse phase window start referred to (C);
- N Pulse phase window end referred to (I), the "collet entry slowdown" (G) simultaneously ends.



INFORMATION

DEFAULT VALUE PROGRAMMABLE VALUE
Kid 80
Kid 80
A 20
/
M 400
/

20

14

N

SIEMENS

0

Pulse window start

Pulse window end

20

no. 14 Pulse number

Pul.with closed collet

To prevent unnecessary machine stops, it is recommended to enter a high value in the subparameter (M).

-

INFORMATION

If the bar meets an obstacle before entering the pulse window section, the bar feeder goes into "ALARM" (15 Stationary position before pulses).

C = Collet outer alignment Parameter 64; I = Facing (Parameter 64 + Parameter 2), in the example in the picture the hypothetical value entered in Parameter 2 = 100 mm. The value can be either positive or negative, for further information see Parameter 2.





no. 15 Pulse stroke

Defines the length of the forward and backward stroke of the pulses (see parameter 14).



no. 18 Spindle pulses - on-time

Defines the duration of the ON pulse that the lathe receives to make the spindle turn. This is necessary to simplify the entry of the shaped bars into the collet. Description of the phase order:

- the bar moves into the slowdown section (see parameter 11);
- the bar meets the obstacle (the collet) and the lathe receives the pulses to start turning the spindle for the set time;
- the spindle slows down and then stops (for the time defined in parameter 19);
- the bar receives the feeding pulse;
- if the bar is fed into the collet, the cycle goes on;
- if the bar does not enter into the collet, the previous phases will be repeated.



DEFAULT VALUE	PROGRAMMABLE VALUE		
Kid 80	Kid 80		
0.5	/		



KID 80 SIV

no. 19 Spindle pulses - off-time

Defines the duration of the OFF pulse given to the lathe to slow down and stop the spindle, prior to the following rotation pulse (see phase description in parameter 18).



DEFAULT VALUE	PROGRAMMABLE VALUE		
Kid 80	Kid 80		
0.5	/		

no. 20 Cycle start delay

When the bar is in the facing position (see parameter 2), the "cycle start" signal of the lathe can be delayed for a preset value (K15). Application example: it is necessary to have the "cycle start" signal delay when the spindle needs a certain time to reach the operating rotation speed.



DEFAULT VALUE	PROGRAMMABLE VALUE		
Kid 80	Kid 80		
0	/		

KID 80 SIV

no. 21 Remnant handling

- 0 (Removal) (Subparameter Off)
- 1 (Ejection)
- 2 (Bar change advance no first feeding)
- 3 (Bar change advance no facing)

0 - (Removal) (Subparameter Off)

Description of the phase order:

- at the bar end, the bar pusher and the remnant are in the spindle of the lathe;



DEFAULT VALUE	PROGRAMMABLE VALUE		
Kid 80	Kid 80		
1	0/1/2/3		



- the bar pusher and the remnant reach the "completely backwards" position, the remnant is removed from the collet and falls into the remnant recovery box.



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KID 80 SIV

Mode 1 - (Ejection) 2 - (Bar change advance) 3 - (Bar change advance, no facing) Foreword

To enable one of the two modes, the lathe should have a subprogramming function. The subprogram should control the bar stop removal at the bar end signal. The bar stop removal allows the ejection of the remnant from side (A) of the lathe.





1 - (Ejection)

It is possible to choose among the two following solutions:

- a) Ejection with the new bar.
- b) Ejection with the bar pusher.
- a) Ejection with the new bar. Description of the phase order:

(B) - The lathe receives the "BAR END" signal from the bar feeder, finishes the machining of the last piece, then goes in the subprogram (bar stop removal) and sends the "FEEDING" and the "BAR CHANGE" signals;



(C) - The bar pusher moves up to point F (maximum feeding point of the bar pusher) and the bar feeder carries out the bar change;

(D) – Through the feeding, the new bar ejects the remnant and moves into the facing position.



b) Ejection with the bar pusher.



KID 80 SIV

Move point F (maximum bar pusher feeding point, see parameter 29) to the collet alignment. Description of the phase order:

PHASE 1 - the lathe receives the "BAR END" signal from the bar feeder, finishes the machining of the last piece, then goes in the subprogram (bar stop removal) and sends the "FEEDING" and the "BAR CHANGE" signals;

PHASE 2B - the bar pusher moves up to point F, ejects the remnant and the bar feeder carries out the bar change.



2 - (Bar change advance no first feeding)

Allows the bar feeder to carry out the bar change while the lathe has started machining the last piece. Thus, the bar change starts in advance, i.e. before the last piece machining ends and the bar pusher attains point F. The remnant is ejected only with the new bar.

Necessary conditions.

- Set the interface signal 85 "LOADING CYCLE", in position 1 (=NC) and set parameter 21, "REMNANT HANDLING", in mode 2.
- use the "BAR CHANGE ADVANCE" lathe signal (applicable only to lathes which have this function).

Description of the phase order:

- the lathe receives the "BAR END" signal, with the above mentioned conditions;
- the bar feeder carries out the return of the bar pusher and loads a new bar in the guide channels whilst awaiting the "FEEDING" and "BAR CHANGE" signals;
- as soon as the last piece has been machined, the lathe enters the subprogram (bar stop removal) and sends both the "BAR FEEDING" and "BAR CHANGE" signals
- the new bar moves forwards, ejects so the remnant and reaches the facing position.

3 - (Bar change advance no facing)

Allows the bar feeder to carry out the bar change while the lathe has started machining the last piece. Thus, the bar change starts in advance, i.e. before the last piece machining ends and the bar pusher attains point F. The remnant is ejected only with the new bar.

Necessary conditions.

- Set the interface signal 85 "LOADING CYCLE", in position 1 (=NC) and set parameter 21, "REMNANT HANDLING", in mode 3.
- Use the "LOADING CYCLE" lathe signal (applicable only to lathes which have this function).

Description of the phase order:



- the lathe receives the "BAR END" signal, with the above mentioned conditions;
- the bar feeder carries out the bar pusher return, loads a new bar in the guide channels, carried out first feeding and bar loading in the bar feeder collet and then awaits the "FEEDING" and "BAR CHANGE" signals;
- as soon as the last piece has been machined, the lathe enters the subprogram (bar stop removal) and sends both the "BAR FEEDING" and "BAR CHANGE" signals;
- the new bar begins the facing phase until it reaches the position indicated in parameter 2, the bar feeder sends the cycle start signal to the lathe.



KID 80 SIV

no. 22 Open collet timeout

This is the maximum duration time of the FEEDING phase ("OPEN COLLET"). If for any reason the bar feeder remains with the feeding enabling signal ("FEEDING" signal from lathe) for a longer time than the set one, it goes in "ALARM".



DEFAULT VALUE	PROGRAMMABLE VALUE		
Kid 80	Kid 80		
0	/		

no. 23 Piece timeout

This is the maximum duration of the piece machining.

If for any reason the period for machining of a piece exceeds the set time, the bar feeder will activate the "ALARM".



DEFAULT VALUE	PROGRAMMABLE VALUE		
Kid 80	Kid 80		
0	/		



no. 25 Bar feeding handling

0 - (FEEDING END WITH BAR CHANGE): the bar feeder will stop feeding when the BAR CHANGE signal is received.

1 - (FEEDING END WITH K1): in the presence of the BAR END (K1) signal, the bar feeder stops the feeding.



no. 26 Pieces before the lathe stop

VALUE 0 - The parameter function is disabled. VALUE >0 - When the set value of pieces machined is reached, the bar feeder calls the stop of the lathe whilst "FEEDING".



DEFAULT VALUE	PROGRAMMABLE VALUE		
Kid 80	Kid 80		
0	0/>0		

VALUE >0 - Application example. 1.Set value at 1000:

the display shows:

SIE	ME	NS	SIMATIC HM			I	
no.	26	Pieces	before	lath	ne stop		Η
			:>1	L000	(0)		00
							S
						_	



KID 80 SIV

2.Start machining. After finishing 1,000 pieces, the bar feeder will command the lathe stop.

the display shows:

To restart machining, the value in brackets should be reset.





no. 27 Minutes before the lathe stop

VALUE 0 - The parameter function is disabled. VALUE >0 - When the minutes set have passed, the bar feeder signals the lathe to stop "FEEDING".



no. 28 Closed collet speed

Defines the "CLOSED collet" speed value.

28	SIEMEN	S		SIMATIC	HMI
	<u>no. 28</u>	Closed co	llet sp +20	veed Vinax	TOUCH
	DEFAULT	VALUE	PRC	GRAMMABLE	VALUE
	Kid 20	80		Kid 80	



KID 80 SIV

no. 29 Max. feeding pos. adjustment

Defines the adjustments (+ or -) of point F (maximum bar pusher feeding point).

Application examples:

- necessary when working with the bar pusher ejection (see parameter 21, point b);
- necessary when the lathe collet is replaced with one of different dimension.





When the adjustments of point F are performed, parameter 1 is modified as shown in the figure.

- A No adjustment
- B With adjustment +, for example + 10
- <u>C With adjustment -, for example 10</u>



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no. 30 Language 1I

Defines the language of the information that appear on the display:









no. 32 K1 immediate exit

0 - (with open collet K1 is not activated). When detected, the bar end signal K1 is sent to the lathe at the "COLLET CLOSING".

1 - (with open collet K1 is activated). When detected, the bar end signal K1 is immediately sent to the lathe during the "FEEDING" signal.



no. 33 K2 inversion

0 - (K2 is on 1 at limit stop). During the feeding signal, the K2 relay remains off during the bar feeding; it is activated when the bar arrives at the bar limit stop (encoder stop).

1 - (K2 is on 0 at limit stop). The K2 relay is active during the bar feeding and off when the bar reaches the bar limit stop (encoder stop).





no. 34 Feeding torque

Defines the thrust value received by the bar at each "FEEDING".



no. 35 Fixed-piece feeding

0 - (AT THE LIMIT STOP). Carries out the feeding to the bar limit stop.

1 - (AT FIXED VALUES). Carries out the piece feeding, in accordance to the value set in parameter 6.

2 - (AT FIXED VALUES AND THRUST TO THE LIMIT STOP). Carries out the piece feeding according to the value set in parameter 6, stops at few millimetres from the bar limit stop, and then carries out another feeding up to the bar limit stop, until the FEEDING signal is active.

Subparameters:

- B Position
- C Speed
- D Acceleration
- E Deceleration



DEFAULT VALUE	PROGRAMMABLE VALUE
Kid 80	Kid 80
1-Step feeding	0/1/2
0	/
0	/
0	/
0	/



KID 80 SIV

no. 36 K15 disabling

0 - (K15 ENABLED). Enables the warning at every use of parameter 35 in position 1.
1 - (K 15 DISABLED). Disables the warning at every use of parameter 35 position 1.



no. 37 K15 duration

Defines the CYCLE START signal duration.



no. 38 K13 duration

Defines the CYCLE STOP signal duration.

38	SIEMENS		SIMATIC	HMI
	no. 38 K13 I	Duration		
			sec	
D	EFAULT VALUE		PROGRAMMABLE	VALUE
	Kid 80		Kid 80	I
	0		/	



no. 39 Spindle stop

When the bar change is carried out the signal stops the spindle.

0 - (RELAY DISABLED WITH BAR CHANGE). The relay is disabled with the bar change.

1 - (RELAY ALWAYS ENABLED). The relay is always enabled.





KID 80 SIV

no. 40 Bar pusher return at collet closing

Defines the bar pusher backward displacement at each "COLLET CLOSING". This displacement prevents the bar pusher coming into contact with the bar.

Parameter:

A - Position

The subparameters define the speed and acceleration/deceleration during the closed collet bar pusher movement.

- B Speed
- C Acceleration
- D Deceleration

For fixed headstock or sliding rest lathes; set a displacement of some millimetres.





	DEFAULT VALUE	PROGRAMMABLE VALUE
	Kid 80	Kid 80
A	41.131	/
в	50000.000	/
С	95	/
D	95	/

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For sliding headstock lathes; set the value of the headstock stroke plus some millimetres.

- A Headstock stroke +2÷3 mm
- B Headstock stroke





KID 80 SIV

no. 41 First feeding value (B)

During the FIRST FEEDING phase, the carriage stops as soon as it reaches the value set in the parameter.

41	SIEMENS				SIMATIC HMI				
	no.	41	First	feedi	ng	value	(B)		Τ
					c	m	n		2
								_	F
D	EFAU	LT	VALUE			PROGR	AMMABI	LE VALU	JΕ
	Ki	d 8	30				Kid 8	80	
	1	405	5		N	N=1075	L=140	5 LL=1	735

no. 42 Bar pusher return pause

"BAR PUSHER RETURN" signal timing.

42 SIE	MEN	IS		S	IMATIC	HMI
no.	42	Bar	pusher	return	pause	
					sec	
DEFAU	LT VZ	ALUE		PROG	RAMMABLE	VALUE
Ki	d 80				Kid 80	
().2				/	



no. 43 First feeding speed change Allows changing the "FIRST FEEDING SPEED".

Parameter:

- A Speed type
- 0 Slow
- 1 Fast

Subparameters:

- B Speed 1
- C Speed 2
- D Acceleration
- **E** Deceleration



	DEFAULT VALUE	PROGRAMMABLE VALUE
	Kid 80	Kid 80
A	1	/
в	20000	/
С	60000	/
D	100	/
E	15	/



KID 80 SIV

Parameter "Speed change in first feeding" 1 = Fast



Speed - Speed mm/minute

- B Space covered mm
- V1 Speed set in slow section
- V2 Speed set in fast section
- F V1 ramp acceleration
- G V2 ramp acceleration
- H Deceleration
- L Facing flag

Parameter "Speed change in first feeding" 0 = Slow



KID 80 SIV

no. 44 Axis operation

Subparameters:

- A Bar pusher stop with closed collet
- B Axis stop engagement delay
- C Closed collet torque

The subparameters of this parameter control some functions of the bar pusher movement.

Bar pusher stop with closed collet - Axis stop engagement delay

These two subparameters enable the feeding motor stop (axis stop) with CLOSED COLLET, so as to avoid that the bar slides off from the bar pusher collet, due to the machining vibrations.



INFORMATION

The function of these two subparameters is applicable with parameter 24 in modes 0 and 5. It is not applicable with modes 1, 2, 3 and 4.

Bar pusher stop with closed collet

0 - the bar pusher stop is off 1 - the bar pusher stop is on

Axis stop engagement delay

This subparameter allows setting a delay time for the axis stop engagement at every CLOSED COLLET. This period of time allows you to "release" the bar feeder transmission devices, so as to avoid useless tensions.

Closed collet torque

This subparameter allows adjusting the thrust value with which the bar pusher moves the bar during the "CLOSED COLLET" signal.



DEFAULI VALUE	PROGRAMMABLE VALUE
Kid 80	Kid 80
OFF	on/off
1	/
+20	/



KID 80 SIV

1

INFORMATION:

When working with Par.24 =1 (sliding headstock with no synchronization device) the "Closed collet torque" adjusts the thrust value with which the bar pusher moves the bar during the "CLOSED COLLET" signal.

SIEMENS	SI	MATIC	CHMI
no. 44 Axis ope	ration		
Bar pusher stop with closed coll Ands stop engagement delay Torque with closed coll	OFF et • 1 sec +20 et	Cmax	



2.12 ERRORS - CAUSES - SOLUTIONS

During the bar feeder set-up or the piece machining, the display may highlight errors or messages.

Such errors or warnings may be caused by an incorrect programming, an incorrect manoeuvre, or a mechanical or electrical fault.

When the errors are detected the bar feeder stops; to restore the automatic cycle carry out the following procedure:

- restore the manual cycle;
- eliminate the cause of the error;
- restore the automatic cycle.



All messages with "Error" must be reset by pressing

When a warning is displayed the bar feeder does not stop and it is not necessary to reset the machine.

The warnings appear when attempting to perform a manoeuvre which is not allowed by the program and provide information for the operator during the machining.



KID 80 SIV



INFORMATION:

Some alarms have the same name as the sensor that triggered them (for example "10-Bar feeder emergency S610.1"). The position of the sensor or button can be located by means of the description shown on the display or by means of the label inside the magazine guard.
2 - INFORMATION FOR USE

Button with the "general warning" symbol, allows you to view the type of alarm causing the machine to stop.

By pressing the 💷 button

The "Guidance text" explaining how to fix the error is displayed.





feeder emergency

-1,318

1

STEP BY STEP

Pos. da

+1601,318

AUT 0-ASSE

IEMCA

MAN

SIEMENS



SIMATIC HMI

Vj

>>





EN 2 - INFORMATION FOR USE

KID 80 SIV

Press, the layout showing the position of the bar feeder sensors is displayed.









INFORMATION:

the alarms referring to a specific working phase are identified within the "operating cycle" (see section 3.4).

INFORMATION:

All "Alarms" must be reset by pressing RESET

The alarm messages, their probable causes and related solutions are listed below.



EN 2 - INFORMATION FOR USE

KID 80 SIV

3 - ERROR: THE BAR FAILS TO ENTER INTO THE COLLET

The bar has met the first obstacle in the pulse window as defined in parameter 14 (pulse window start - pulse window end) and has exceeded the entry attempts as defined in the same parameter (pulse number).

CAUSE	SOLUTION	3 EMENS SIMATI
	Check the diameter of the bush.	Warning Bar fails to enter into the collet
The bar does not enter into the collet or into the lathe bush.	If it is a shaped bar, check if the bar entry kirving is correct on the rear part of the collet.	
	If it is a shaped bar, check the spindle rotation and if the pulse sequence is correct.	Pere I Constant Step BY Man AUT 0-ASSE IN CONSTANT OF AUTO
The feeding speed and/or torque are not suitable.	Check the speed (see parameter 12) and/or the torque (see parameter 13).	

4 - ERROR: GATE OPEN (S1008 Off)

Error: AT THE FIRST FEEDING STROKE START, THE SHORT FEED GATE IS OPEN.

CAUSE	SOLUTION	4	EMENS		SIMATIC HMI	
The short feed gate is jammed and cannot be closed.	Make sure that there are no foreign bodies (chips, remnants, fragments) in the short feed gate movement area; carry out the movement manually to find any possible obstacles.		Warning Gate open			TOUCH
Operation failure of the solenoid valve of the short feed gate closing.	Check the electromechanical operation of the device.	o Ia R	Perat C. 100 % I O SE SET STOP AU	MI STEP BY TO STEP MAN	AUT 0-ASSE	
Operation failure of the sensor, which detects the short feed gate closing.	Make sure that to the short feed gate movement corresponds to the sensor state change.					

2 - INFORMATION FOR USE

5 - ERROR: SHORT FEEDING

Error: A BAR PUSHER SHORT FEEDING MOVEMENT HAS BEEN DETECTED IN ACCORDANCE WITH THE SETTINGS OF PARAMETERS 5 and 6.

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KID 80 SIV

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CAUSE	SOLUTION	
The tolerance values of parameters 5 and 6 are too low.	Check the tolerance values with regards to the length of the piece to be machined.	Warning X Short feeding
The lathe collet does not open correctly.	Check the correct opening of the collet (at least 0.5 mm).	CIPERATE PSC PSC PSC PSC PSC PSC PSC PSC
Encoder operation failure.	Check the value relative to the position of the bar pusher carriage on the display and check the effective variation of the value with regards to the real displacement of the carriage.	
The thrust received by the bar is too low.	Check the values of parameters 7, 8 and 34.	"A" - Short piece safety tolerance (subparameter
The bar slides out of the collet during the headstock stroke.	Check the bar pusher collet state.	Par.5), Short feeding safety (subparameter Par.6). "C" - Headstock stroke (Parameter Par.5). Feeding (Parameter Par.6).



EN 2 - INFORMATION FOR USE

6 - LONG FEED

Warning: A BAR PUSHER LONG FEEDING MOVEMENT HAS BEEN DETECTED IN ACCORDANCE WITH THE SETTINGS OF PARAMETERS 5 and 6.

CAUSE	SOLUTION	
The tolerance values of parameters 5 and 6 are too low.	Check the tolerance values with regards to the length of the piece to be machined.	6 MENS SIMATIC HMI
The lathe bar limit stop is not in the correct position.	Check the position of the bar stop on the lathe.	C ID S C ID S
Encoder operation failure.	Check the value relative to the position of the bar pusher carriage on the display and check the effective variation of the value with regards to the real displacement of the carriage.	
Possible breakage of the cutting tool.	Check the condition of the cutting tool.	"B" - Long piece safety tolerance (subparameter Par. 5) or Long feeding
The bar slides out of the collet during the headstock stroke.	Check the bar pusher collet state.	(subparameter Par. 6). "C" - Headstock stroke (Parameter "C" Par.5). Piece feeding (Parameter "C" Par. 6).

7 - ERROR: BAR TOO LONG

Error: DURING THE FIRST FEEDING STROKE OR DURING THE BAR DETECTION STROKE IN THE "START-UP" PROCEDURE A BAR OF LONGER LENGTH THAN THAT SET IN PARAMETER 67 "MAXIMUM BAR LENGTH" IS MEASURED.

CAUSE	SOLUTION	7 EMENS SIMATIC HMI
The bar loaded is longer than the	Reduce the length of the bar loaded.	7 Error: bar too long
67.	Check the value set in parameter 67.	Division Company Division I 0 SEMIL STEP BY I 0 AUTO STEP



8 - PRESET QTY. REACHED, RESET - P26

Warning: THE BAR FEEDER HAS STOPPED AUTOMATICALLY DURING THE MACHINING PHASE.

CAUSE	SOLUTION	8	EMENS	SIMATIC HMI
The set quantity of pieces has been reached.	Reset the number of pieces and restart.		Warning Preset QTY. 1 Preset QTY. 1 Preset QTY. 1 Reset Office State	STEP BY MAN AUT 0-ASSE

9 - OPEN COLLET TIMEOUT

Warning: THE BAR FEEDER HAS STOPPED WITH THE ACTIVE FEEDING SIGNAL SINCE THE OPEN COLLET "TIMEOUT" HAS ELAPSED.

CAUSE	SOLUTION	9 EMENS SIMATIC HMI
In the AUTOMATIC mode the lathe collet remained open for a longer period than the one set in parameter 22.	Check the value of parameter 22, with regards to the real "FEEDING" time.	Warning Open collet timeout

10 - BAR FEEDER EMERGENCY

Warning: THE GENERAL CONTROLS OF THE BAR FEEDER ARE NOT INSERTED.

CAUSE	SOLUTION	10	EME	NS			SIM	ATIC	нмі
An emergency button has been pressed.	Check the state of the emergency button.		Warn Bar fe	ling æder ene	rgency				X
There is an emergency signal from the lathe.	Check whether the signal sequence arriving from the lathe is continuous: the signals must be all on or all off.		p perat						
There is an open guard in the lathe or in the bar feeder.	Check if the guards are closed.		Par. lemca	C 100 % D SEMI OP AUTO	STEP BY M.	IN AUT	T 0-ASSI		



EN 2 - INFORMATION FOR USE

KID 80 SIV

11 - WRONG FACING POSITION

In automatic mode, the facing position has been reached and the overrun position, as defined in subparameter 3, has been exceeded.

CAUSE	SOLUTION
When the bar does not stop in the facing position (parameter 65), but exceeds this point by a value higher than or equal to the set value in the "Overrun admitted after I"	Make sure that the chain is correctly tensioned.
performed only when the "FACING IN POSITION" mode is active and if the set value in the "Overrun admitted after I" subparameter is > 0.	The values for "Facing and overrun admitted after I" set by the operator are wrong.



13 - PIECE TIMEOUT

Warning: THE WORKING CYCLE FOR MACHINING A PIECE HAS TAKEN LONGER THAN THE TIME SET IN PARAMETER 23.

CAUSE	SOLUTION	13 EMENS S	IMATIC HMI
The working cycle for machining a piece has taken longer than the time set in parameter 23.	Check the setting in parameter 23 with regards to the working cycle.	Warning Piece timeout	X
The working cycle for machining a piece has undergone an interruption or a slowdown.	Make sure that the actual duration of the working cycle does not face slowdowns or interruptions.	Por Terror RESET STOP AUTO STEP MAN AUT	



INFORMATION:

The alarm described above also appears when the following conditions are met: in automatic mode with the open collet signal for 1 hour; in automatic mode with the closed collet signal and parameter 24 Synchronization to 1 for 1 hour.

2 - INFORMATION FOR USE



15 - STATIONARY POSITION BEFORE PULSES

In automatic mode, during the facing jog, if the flag has been knocked down and the bar pusher has stooped within the pulse window as defined in parameter 14. During the bar loading phase, the bar pusher moves but it stops before knocking down the facing flag.

CAUSE	SOLUTION	
There is an obstacle inside the spindle	Make sure that there are no obstacles or diameter differences which could interfere with the bar feeding.	SIMATIC HMI
The pulse window defined in parameter 14 has not been set correctly.	Check the value set in parameter 14.	Par Perce L 00 SEMI STEP BY MAN AUT 0-ASSE STOP AUTO STEP MAN AUT 0-ASSE
An inappropriate torque value has been set	Check the set torque value.	A - Parameter 11 B - Area with error 27



EN 2 - INFORMATION FOR USE

KID 80 SIV

IOUCH

16 - AXIAL DISPLACEMENT NOT LOCKED (S1221 Off)

Warning: THE AXIAL DISPLACEMENT SENSOR IS NOT ACTIVE.

CAUSE	SOLUTION	16 EMENS SIMATIC HA
The axial displacement device is not locked.	Lock the axial displacement device.	Warning X Axial displacement not locked (S12210ff)
The sensor is faulty.	Replace the sensor.	
Incorrect reading of the sensor.	Check the distance between the sensor and the relevant cam.	Price C 100 % 1 I

17 - MOTOR THERMAL CIRCUIT BREAKERS (E11.7) A MOTOR THERMAL CIRCUIT BREAKER HAS TRIPPED.

CAUSE	SOLUTION	17 EMENS SIMATIC HMI
The oil pump overheating has	Make sure that the involved motor can run freely and check the correct thermal calibration (according to the amperage).	Warning X Motor thenmal circuit breakers
occurred.	Check the motor input voltage.	Percention Image: Constraint of the second

2 - INFORMATION FOR USE

18 - FAILURE DURING THE BAR CHANGE

Warning: THE BAR CHANGE WAS NOT COMPLETED IN THE PRESET TIME.

CAUSE	SOLUTION	18	EMENS	5	SIMA	TIC HM	I
When an unforeseen mechanical or electrical error occurs, a safety time stops the machine if the bar change cycle does not occur in the preset time.	Check the exact cause of the fault and reset the working cycle.	RES	Warning Failure d rot cct c to v set o stop	g iuring the bar ch sem step by auto step MAN	ange kut 0-Asse		TOUCH

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KID 80 SIV

19 - NO BAR

IN AUTOMATIC MODE, THE MECHANICAL FEEDING IS ACTIVATED BUT ITS PROCEDURE HAS NOT BEEN COMPLETED AND THE COMPLETELY CLOSED CLAMP SENSOR IS ON.

CAUSE	SOLUTION	19 EMENS	SIMATIC HMI
The phase detector is not working properly.	Make sure that the phase detector on	Warning No bar	X
There is a mechanical obstacle	the mechanical cam works properly	PSU Lenco I O SEMI STEP BY RESET STOP AUTO STEP MAN	AUT 0-ASSE A

22 - MACHINE OK!

THIS IS A MESSAGE AND DOES NOT NEED A RESET. IT IS USED ONLY TO SEND AN SMS OR AN EMAIL INFORMING ON THE AUTOMATIC RESET AFTER AN ALARM.

CAUSE	SOLUTION	22 EMENS	SIMATIC HMI
This message appears for a few seconds when the bar feeder is in automatic mode and the error has been eliminated.	Example: after resetting the emergency mushroom-head button.	Warning Machine CK!	T DASSE



INFORMATION:

This message is used to send an sms or an email informing on the automatic reset after an alarm. It can only be used by customers with IT infrastructures that allow the connection of IEMCA bar feeder to the corporate network.



EN 2 - INFORMATION FOR USE

KID 80 SIV

24 - THREAD SAFETY

Warning: THE LATHE HAS NOT CARRIED OUT THE THREADING OPERATION ON THE PIECE TO BE MACHINED.

CAUSE	SOLUTION		24 EMENS SIM					SIMATIC HMI			
Threading device failure.	Check the effective functioning of the lathe device.		Wa: Thr	rning æd sa	J fety						× OO
Threading controlling device failure.	Check the microswitch placed on the cam box of the thread safety.		P operat								
The bar did not move to the last "COLLET OPENING".	Make sure that the lathe collet opens correctly and check the bar feeder thrust (parameter 34).		Par. lemca I RESET	C. 100 %	SEMI ST AUTO	TEP BY STEP	MAN	AUT	0-ASSE		

25 - CARRY OUT THE 0-AXIS AFTER A POWER OFF-ON

THE ENCODER VALUE PRESET OPERATION WAS NOT CARRIED OUT CORRECTLY IN THE PRESET TIME.

CAUSE	SOLUTION	25 EMENS SIMATIC HMI
The PLC and drive connection cable is broken.	Contact lomas convice department	Warning X 25 Carry out the 0- axis after a power off-on
The drive is faulty.	Contact ferrica service department.	Level C. 100 % Level C. 100 % C. 1

2 - INFORMATION FOR USE



2.13 PROGRAM IDENTIFICATION DATA: DISPLAY MODE

The two following programs have been installed in the bar feeder:

- Push-button panel software;
- PLC/NC Software.

For many reasons (for example the request of assistance) it could be useful to display and understand the program identification data of these

programs using the following procedure.

1. Enter the main screen:

To display the identification data of the "Push-button panel software" of the "PLC/NC Software".____

- 2. Select *i* mode to
- 3. Display the screen where it is displayed:

identification data of the push-button panel software: [barra] SwOP:xxxxx [barra] PLC/NC software identification data: [barra] SwCNC:xxxxx [barra] SIEMENS SIMATIC HM roject name: KID reated: 01/01/2015 uthor: Electrical Engineering Department escription: Bar feeder wTP v 0.1 wPLC v 0.2







INDEX

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KID 80 SIV

3.1 **PROTECTED PARAMETERS: DISPLAY**

These parameters refer to the bar feeder configuration and the bar feeder-lathe interfacing. The modification procedure is mainly necessary during the installation of the bar feeder by an authorized technician.

Data entering or modifying in these parameters is possible only by using the special data entering mode.

To access this mode, it is necessary to follow the procedure given in Section 4.2. The pages of this section are only supplied to the technician authorized by the manufacturer.



The parameters are set to a default value (preset value): the bar feeder performs the automatic cycle according to these values.

The main display modes are the following:

- Access the protected parameters
- Display the protected parameters
- Display the protected subparameters
- Exit the protected parameters

3.2 HOW TO ACCESS AND DISPLAY THE PROTECTED PARAMETERS

- 1. Enter the "main screen"
- 2. Select "Iemca parameters"





"Connection" mode is displayed







7. Select "BROWSE THE LIST"



- Should you need to check and modify parameters between 46 and 100, please contact Iemca Service Department
- 4. Select "Iemca parameters"

3. Enter "Password" number, then 🗲

INFORMATION:



KID 80 SIV

8. If the code is correct, the display will show the first protected parameter:





9. To display the protected parameters press:

the display shows, for example:



- 10. Or, to display the desired parameter, start from step 6 and select "SELECT the NUMBER"
- 11. "OPERATOR Parameters Selection" screen will be displayed on the screen, press:

SIEMENS	SIMATIC HMI
SIEMENS	SIMATIC HMI
IEMCA PA Sele Enter Paramet SENETCAR BROWSE	arameters ection er No. (0.100) PryNUHFFR. the LIST



11. Enter the parameter number, for example "47"; the parameter value changes from 0 to 47;







13. The display will show parameter 47:

47 EMENS SIMATIC HMI

3.3 PROTECTED PARAMETERS: DESCRIPTION

Protected parameters are divided into the following sections:

- Parameters for the reference values (§ 3.4)
- Parameters for the axis functions (§ 3.5)
- Interface parameters (§ 3.6)
- General parameters (§ 3.7)



KID 80 SIV



3.4 PARAMETERS FOR REFERENCE VALUES: DESCRIPTION

- 0) BAR FEEDER ZERO SETTING
- 1) Carriage in its "completely backwards position"
- 2) Bar pusher in its "completely backwards position"
- 3) Carriage in "completely forwards position"
- 4) Short feed gate (flag)
- 5) Bar pusher in its "completely forwards position"
- 6) Spindle
- 7) Headstock in its "completely backwards position"
- 8) Headstock in its "completely forwards position"
- 9) Rest in its "completely backwards position"
- 10) Rest in its "completely forwards position"

(X)Fixed headstock lathe

- (Y)Sliding headstock lathe
- (Z)Sliding rest lathe



no. 60 First feeding value (B)

This parameter value should be entered. This is the value of the first feeding stroke, that is the distance between the front edges of the first feeding carriage in "After removal movement" and "first feeding limit switch" position (point B).



DEFAULT VALUE	PROGRAMMABLE VALUE
Kid 80	Kid 80
1720	/

no. 61 Feeding value (x)

This is the stroke value for the bar loading into the bar pusher collet.





KID 80 SIV

no. 62 Bush value (BO) (Parameter Off)

This parameter value should be entered. This is the position of the bar pusher carriage where the half-bushes are opened; it can be modified with parameter 16.

62 SIEMENS	SIMATIC HMI
no. 62 Bush value	e (BO)
DEFAULT VALUE	PROGRAMMABLE VALUE
Kid 80	Kid 80
	32 N=2390 L=2060 LL=1730
2270	37 N=2930 L=2600 LL=2270
	44 N=3590 L=3260 LL=2930

no. 63 Flag-collet distance (B1C)

This parameter value should be entered. This is the value of point C (facing point), that is the distance from the short feed gate 12 (of the bar feeder) and the front edge of the lathe collet.





no. 64 Collet value (C)

The value of this parameter is predefined by the program.

Distance (mm) that the bar pusher has to travel to reach point C after the bar first feeding.



no. 65 Collet + facing value (C1)

The value of this parameter is predefined by the program.

The number is given by the value of point C in addition to the value of parameter 2.

65	SIEN	MENS			SIMA	TIC HM	1
	no.	65 Col	let +	facing	value	(CI)	T
					mm		<u>S</u>
							R
							A REPORT OF THE PARTY OF THE PA
	DEFAUL	T VALUE	1	PR	OGRAMM	ABLE VAL	JUE
	Kid	1 80			Ki	d 80	

1

preset value



KID 80 SIV

no. 66 Maximum feeding value (F)

The F point is the maximum bar pusher feeding point: this value corresponds to the bar pusher stroke from its completely backwards position to point F.

This value changes according to the different applications and should be entered by the Installation Technician (see default value on the side).





no. 67 Lubrication stop value (L) (Parameter Off)

This parameter value should be entered. Value where the oil pump motor for the lubrication of the guide channels stops.



no. 68 Guide channel opening max. value

The value of this parameter is predefined by the program.

Position of the feeding carriage when the guide channels open.





KID 80 SIV

no. 69 Maximum bar length

This parameter value should be entered. Set the max. length of bars that are to be loaded.







OPERATING CYCLE - DESCRIPTION





KID 80 SIV



INFORMATION:

**after powering the machine on or off, the first bar change cycle involves PHASE 3, consisting in a slow movement to "0 position" in order to check that the "0 position" coincides with the 0-Axis sensor (S1235) activation.





KID 80 SIV

3.5 AXIS FUNCTION PARAMETERS: DESCRIPTION

no. 70 FCMax

Defines the moving axis parameterization.

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INFORMATION

Once the values for parameter 70 have been set, turn off the power supply and then turn it on again, if you want the preset values to be self-learned. We recommend not to modify these parameters. However, if a modification is necessary, contact IEMCA service department.



51

INFORMATION:

The "FCMax" subparameter is the maximum value the bar pusher can reach during feeding. Therefore, these values have to be considered in all the parameters where a speed value may be set.

no.71 Speed reduction in manual mode

Defines the speed value by which the bar pusher moves in manual mode. This value is expressed as a percentage of the maximum speed.

Parameters:

A - Speed reduction in manual mode

Subparameters:

- B Forwards slowly
- C Forwards fast
- D Backwards slowly
- E Backwards fast





no. 72 Speed reduction during bar change

Defines the speed value by which the bar pusher moves during the bar change cycle in the phases described by B, C, D, E subparameters. This value is expressed as a percentage of the maximum speed. Parameters:

A - Speed reduction during bar change

Subparameters:

B - From collet entry slowdown to pulse window end

- C Pulse backwards
- D Facing to limit stop
- E Facing jog



	DEFAULT VALUE	PROGRAMMABLE VALUE
	Kid 80	Kid 80
A	/	/
в	6	/
C	20	/
D	10	/
Е	28	/

no. 73 Limitation of automatic speed

Defines the speed value by which the bar pusher moves in automatic mode. This value is expressed as a percentage of the maximum speed.

Parameters:

A - Limitation of automatic speed

Subparameters:

- B Collet closed
- C Collet open



	DEFAULT VALUE	PROGRAMMABLE VALUE
	Kid 80	Kid 80
A	/	/
в	20	/
С	30	/



KID 80 SIV

no.77 Torque reduction in manual mode

Defines the torque value by which the bar pusher moves in manual mode. This value is expressed as a percentage of the maximum torque.

Parameters:

A - Torque reduction in manual mode

Subparameters:

- **B** Forwards slowly
- C Forwards fast
- D Backwards slowly
- E Backwards fast



	DEFAULT VALUE	PROGRAMMABLE VALUE
	Kid 80	Kid 80
A	/	/
в	40	/
С	70	/
D	70	/
Е	70	/

no. 78 Toque reduction during bar change

Defines the torque value by which the bar pusher moves during the bar change cycle in the phases described by B, C, D, E subparameters. This value is expressed as a percentage of the maximum torque.

Parameter:

A - Torque reduction during bar change

Subparameters:

- B From collet entry slowdown to pulse window end
- C Pulse backwards
- D Facing to limit stop
- E Facing jog



	DEFAULT VALUE	PROGRAMMABLE VALUE		
	Kid 80	Kid 80		
A	/	/		
в	40	/		
С	100	/		
D	35	/		
Е	50	/		



no. 79 Torque reduction in automatic mode

Defines the torque value of the bar pusher in automatic mode. This value is expressed as a percentage of the maximum torque.

Parameters:

A - Limitation of automatic speed

Subparameters:

- B Collet closed
- C Collet open



	DEFAULT VALUE	PROGRAMMABLE VALUE
	Kid 80	Kid 80
A	/	/
в	10	/
C	40	/

no. 84 Keyboard on the opposite side

Allows setting the direction of the controls for the bar pusher movements.

The setting of this parameter should be done with regards to the position of the keyboard i.e.: if it is on one side or on the opposite side. 0 - Defines the movements, forwards and backwards, in both directions.

1 - Defines the movements, forwards and backwards, of the opposite directions with regards to 0.



DEFAULT VALUE	PROGRAMMABLE VALUE	
Kid 80	Kid 80	
1	0/1	



KID 80 SIV

3.6 INTERFACE PARAMETERS: DESCRIPTION

no. 85 Interface signals

Defines how to manage the interface signals from the lathe to the bar feeder.

Subparameters:

- A NO-E0.0Auxiliary enabling1
- B NO-E0.1Auxiliary enabling2
- C NO-E8.0Bar change
- D NO-E8.1Feeding
- E NO-E8.2Manual feeding
- F NO-E8.3Manual return
- G NO-E8.4Man-Aut from lathe
- H NO-E8.5Loading cycle
- I NO-E8.6Feeding stop
- NOT IMPULSIVE
- L NO-E8.7Door safety
- M NO-E9.0Thread safety
- N NO-E9.1Start from lathe
- O NO-E9.2Safety from lathe
- P NO-E9.3Startup
- Q NO-E9.7Working mode



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SIMATIC HMI

3.7 GENERAL PARAMETERS: DESCRIPTION

no. 89 Fair demo

0 - off

1 - on To activate this mode, it is necessary to set parameter 35 at 1, parameter 6 (for example) at 200 mm, and parameter 85 "Bar Change" at 1.

To activate this mode, it is necessary to set parameter 35 at 1, parameter 6 (for example) at 200 mm, and parameter 85 "Bar Change" at 1.

no. 90 Wrong bar feeder phase

0 - (K37 active with closed guide channels in manual mode).

During the "MANUAL" cycle, the bar feeder goes into "ALARM" when performing movements (for example "guide channel opening"). The bar feeder "WORKING" phase is lost and must be re-established; the "BAR FEEDER WAITING" message will be displayed.

1 - (Bar feeder in manual mode and lathe in automatic mode).

At the first bar feeding signal, the bar feeder goes into "ALARM" mode if it is in manual mode.



 DEFAULT VALUE
 PROGRAMMABLE VALUE

 Kid 80
 Kid 80

 ON
 ON/OFF

CIN

90	SIEMENS	SIMATIC HMI
	no.90 Wrong bar f	eeder phase
	0-K37 active with closed	l guide channels in the manual mode
		▶≚
Ε	DEFAULT VALUE	PROGRAMMABLE VALUE
	Kid 80	Kid 80
	0	0/1

After the "MANUAL/AUTOMATIC" lathe signal is given, this safety is not activated if the bar feeder is working in "MANUAL" mode from the lathe.

89

SIEMENS

no. 89 Fair Demo



KID 80 SIV

no. 98 Indicators

The parameter describes "Speed" and "Torque" instant values during the bar feeder working phase. It is not possible to interact with or to modify the values displayed, which are only given as an indication.


IEMCA *KID 80 SIV* EN

no. 99 SMS

SMS address where to deliver messages.

- A Address
- B Subject
- C Text



no.100 E-mail

The e-mail address where the e-mail should be sent in case of bar feeder alarm can be set directly from the touch screen.

- A Address
- B Subject





INDEX

5.1	ASSISTANCE REQUEST	2
A	HARDWARE AND PROGRAM IDENTIFICATION DATA	3
В	PARAMETER LIST FOR THE OPERATOR	4
D	PARAMETER LIST FOR THE REFERENCE VALUES	8
E	PARAMETER LIST FOR THE AXIS FUNCTIONS	9
F	PARAMETER LIST FOR THE INTERFACE	.1
G	GENERAL PARAMETER LIST1	.2



5.1 ASSISTANCE REQUEST

For assistance request, send the list of parameters with the assigned values (attachments B, C, D, E, F, G) to IEMCA service department.

In addition, it is necessary to transmit the identification data of the HARDWARE installed in the bar feeder (attachment A).

EXAMPLE OF FILLING IN

ndello caric; odello macc r. 1 Regolazio 2 Lunghezzi 3 Modo di ir 4 Sicurezza	tore Gen tus 112 hina utilizzatrice Ten to 224 ELENCO DEI PARAMETRI Descrizione parametro	PER L'OPERAT	1382	70					D			
r. 1 Regolazio 2 Lunghezzi 3 Modo di ir 4 Sicurezza	hina utilizzatrice Rex 10 224 ELENCO DEI PARAMETRI Descrizione parametro	PER L'OPERAT				/99						
r. 1 Regolazio 2 Lunghezzi 3 Modo di ir 4 Sicurezza	ELENCO DEI PARAMETRI Descrizione parametro	PER L'OPERAT							<u> </u>	F		
r. 1 Regolazio 2 Lunghezza 3 Modo di ir 4 Sicurezza	ELENCO DEI PARAMETRI Descrizione parametro	PER L'OPERAT					/99					
r. Regolazio 2 Lunghezza 3 Modo di iri 4 Sicurezza	Descrizione parametro	PER L'OPERAT			_				19			_
r. Regolazio 2 Lunghezza 3 Modo di ir 4 Sicurezza	Descrizione parametro		Valo	re						100	\square	- IG
1 Regolazio 2 Lunghezzi 3 Modo di in 4 Sicurezza		Fase	asseg	nato	Pag.							, i
2 Lunghezzi 3 Modo di ir 4 Sicurezza	ie fine barra	lavoro	120	mm	14	Pag					199	
 Modo di ir Sicurezza 	ı intestatura	cambio barra	40	mm	14	1m +4						/99
1 Sicurezza	,estatura	cambio barra	1		14	m 14	P	ay.				
Cinum	avanzamento corto	lavoro	20	mm	14	14	im	14	Pag.			
Sicurezza	avanzamento lungo	lavoro	20	mm	14	1m 14	ım	14				
7 Velocità n	nza anerta	lavoro	10	mm/sec	14	im <i>14</i>		14	14	Pag.		
3 Accelerazi	one pinza aperta	lavoro	2	mlear2	14	im 14	im -	14	14	ım 14	Pag.	
P Ritardo so	nta pinza aperta	lavoro	3	Sec	15	ec 14	nm	14 m	14	im 14		
) Ritardo sp	nta pinza chiusa	lavoro	3	Sec	15	c ² 14	im	14 Im	14	14	m 14	Pag
1 Rallentam	ento ingresso pinza	cambio barra	40	mm	15	6C 15	2	14 Im	14	m 14	111 7.4	m 14
2 Velocită in	jresso pinza	cambio barra	10	mm/sec	15	ec 15	C-	15 6C	14	m 14	m 14	m 14
4 Numero d	gli impulsi	cambio barra	3		15	im 15	ec	15 C ²	14	m 74	m 14	14
5 Corsa imp	ulsi	cambio barra	20	mm	15	ec 75	ım	15 ec	15	ec 14	m 14	m 14
6 Apertura k	occola	lavoro	10	mm	15	15 10 15	ec	15 ec	15	$C^2 = 14$ BC = 15	ec 14	m 14
7 Chiusura I	occola	cambio barra	10	mm	15	im 15		15 IM	15	ec 15	c ² 14	m 14
3 Impulsi ma	ndrino-tempo on	cambio barra	3	Sec	16	nm 15	im i	15 ec	15	im 15	ec 15	6C 14
 Ritardo pa 	rtenza ciclo	cambio barra	3	86C	10	oc 18	ım	15	15	0C 15	ec 15	C ² 14
Gestione r	ello spezzone	cambio barra		200	16	ec 16	m	15 m	15	15	m 15	6C 15
Uso sincra	nismo	lavoro	0		16	ec <i>16</i>	ec	16 m	15	m 15	ec 15	m 15
5 Pezzi prim	a dell'arresto tornio	lavoro	250		16	16	ec	16 ec	16	m 15	15	6C 15
7 Minuti prin	a dell'arresto tomio	lavoro	/	min	16	16	ec	16 60	16	111 15	m 15	15
3 Velocită pi	nza chiusa	lavoro	40	V	16	16		76 16 60	16	ec 16	m 15	m 15
Gorrezion	pos. max avanzamento	lavoro	20	N		nin <u>16</u>		16	16	OC 16	ec 16	m 15
) Lingua		1	1	11		/ ¹⁶	nin	16	16	ec 16	ec 16	m 15
1 Uso interfa	cce macchina	1	0	113		-	V	16	16	76	ec 16	ec 16
2 Escl. chius	ura guide in preavanz.	cambio barra					ım	17 in	16	10	16	6C 16
5 Avanzame	nto a pezzo fisso	lavoro	<u> </u>	3	4			17 V	16	nin 16	16	ec 16
Durata K1	2	cambio barra	- 4V	Sec	17	17		17 IM	17	V 16	16	16
o Durata K1)	cambio barra	8	Sec	17	6C 17		17	17	m 17	10 16	16
						6C 17		17	17	17	V 16	16 nin 16
							6C	1/	17	17	m 17	V 16
							υC	6C	17	17	77	m 17
								ec	17	17	17	17
										ec 17	17	17
										6C 17	6C 17	17
											0C 17	17
												ec 17
	L											ec 1)

A HARDWARE AND PROGRAM IDENTIFICATION DATA

Customer	Date
Bar feeder model	Y/N
Machine tool model	

HARDWARE IDENTIFICATION DATA			
	Model:		
CFU CAND	Serial number		
	Model:		
ENABLING CARD (motor drive)	Serial number		

Above data can be found in the "CPU" and "motor enabling" cards, which are located in electric board.

PROGRAM IDENTIFICATION DATA				
PUSH-BUTTON PANEL FIRMWARE	Number:			
PUSH-BUTTON PANEL SOFTWARE	Number:			
PLC/CN SOFTWARE	Number:			
PLC/CN FIRMWARE	Number:			

To trace these data, see section 2.12



KID 80 SIV

B PARAMETER LIST FOR THE OPERATOR

Customer	Date
Bar feeder model	S/N

OPERATOR PARAMETER LIST						
		Default value		Unit of		
Par.No.	Parameter description	KID IV	value	measuremen t		
1	Bar end adjustment			mm-inches		
	Bar end adjustment	100		mm-inches		
	Bar end adjustment (K1A)	300		mm-inches		
	Bar end adjustment (K1B)	500		mm-inches		
2	Facing length	0		mm-inches		
3	Facing mode 0= at limit stop 1= in position	1				
	Overrun admitted after "I"	0		mm-inches		
	Facing to the limit stop	10		%Vmax		
	Facing to the limit stop	35		%Cmax		
4	Short feeding safety	0		mm-inches		
5	Long feeding safety	0		mm-inches		
6	Piece length	0		mm-inches		
7	Open collet speed	30		%Vmax		
9	Open collet thrust delay	0		Sec		
10	Closed collet thrust delay	0		Sec		
11	Collet entry slowdown	200		mm-inches		
12	Collet entry speed	6		%Vmax		
13	Collet entry torque	40		%Cmax		
14	Pulse number	20				
	Pulse window start	400		mm-inches		
	Pulse window end	20		mm-inches		
15	Pulse stroke	0.15		Sec		

5 - ATTACHMENTS

IEMCAKID 80 SIVEN

Customer	Date
Bar feeder model	S/N
Using machine model	

OPERATOR PARAMETER LIST						
Par.No.	Parameter description	Default value KID IV	Allocated value	Unit of measuremen t		
18	Spindle pulses – on time	0,5	0,5	Sec		
19	Spindle pulses – off time	0,5	0,5	Sec		
20	Cycle start delay	0	0	Sec		
21	Remnant handling 0= safety 1= ejection 2= bar change advance (no first feeding) 3= bar change advance (no facing)	0	0			
22	Open collet timeout	0	0	Sec		
23	Piece timeout	0	0	Sec		
25	Bar feeding handling 0=end of feeding with bar change 1=end of feeding with K1	1	1			
26	Pieces before lathe stop	0	0	(0)		
27	Minutes before lathe stop	0	0	Min.		



KID 80 SIV

Customer	Date
Bar feeder model	S/N
Using machine model	

OPERATOR PARAMETER LIST					
		Default value	Allocated	Unit of	
Par.No.	Parameter description	KID IV	value	measuremen t	
28	Closed collet speed			%Vmax	
29	Max feeding pos. adjustment	0		mm-inches	
30	Language 1I-2GB-3D-4F-5E-6S-7DK-8P- 9NL-10FIN-11CS-12RU	1			
32	K1 immediate exit 0=with open collet K1 not activated 1=with open collet K1 activated	0			
33	K2 Inversion 0=K2 is on 1 at limit stop 1=K2 is on 0 at limit stop	0			
34	Feeding torque	40		%Cmax	
35	Fixed-piece feeding 0=at the limit stop 1=at fixed values 2=fixed values + thr. at limit stop	0			
	Position	/			
	Speed	76200			
	Acceleration	100			
	Deceleration	100			
36	K15 disabling 0= K15 included 1=K15 excluded	1			
37	K15 duration	2		sec.	
38	K13 duration	2		sec.	
39	Spindle stop 0=relay disabled during bar change 1=relay always enabled	0			
40	Closed collet bar pusher return	10		mm-inches	
41	First feeding value (B)	1720		mm-inches	
42	Bar pusher return pause	0.2		sec.	

5 - ATTACHMENTS

KID 80 SIV

Customer	Date
Bar feeder model	S/N
Using machine model	

OPERATOR PARAMETER LIST					
	Parameter description	Default value	Allocated	Unit of	
Par.No.		KID IV	value	measuremen t	
	Speed change in first feeding				
43	0=slow	1			
	1=fast				
	Speed 1	9144		Mm/m	
	Speed 2	48000			
	Acceleration	100			
	Deceleration	10			
44	Axis operation				
	Bar pusher stop with closed collet				
	0=the bar pusher stop is off	0			
	1=the bar pusher stop is on				
	Axis stop engagement delay	1		sec.	
	Closed collet torque	10		%Cmax	

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D PARAMETER LIST FOR THE REFERENCE VALUES

Customer	Date
Bar feeder model	S/N

PARAMETER LIST FOR THE REFERENCE VALUES					
Par. No.	Parameter description	Default value KID IV	Allocated value	Unit of measurement	
60	First feeding value (B)	1720		mm-inches	
61	Feeding value (x)	/		mm-inches	
62	Bush value (BO)	2270		mm-inches	
63	Flag-collet distance (B1C)	1400		mm-inches	
64	Collet value (C)	##		mm-inches	
65	Collet + facing value (CI)	##		mm-inches	
66	Maximum feeding value (F)	3740		mm-inches	
67	Lubrication stop value (L)	2590		mm-inches	
68	Guide channel opening max. value	##		mm-inches	
69	Maximum bar length	##		mm-inches	

E PARAMETER LIST FOR THE AXIS FUNCTIONS

Customer	Date
Bar feeder model	S/N

	PARAMETER LIST FOR THE AXIS FUNCTIONS					
Par. No.	Parameter description	Default value	Allocated value	Unit of measureme nt		
		KID IV				
70	FCMax	0				
71	Speed reduction in manual mode					
	Forwards slowly	15,0		%Vmax		
	Forwards fast	50,0		%Vmax		
	Backwards slowly	20,0		%Vmax		
	Backwards fast	50,0		%Vmax		
72	Speed reduction during bar change					
	From "collet entry slowdown" to "pulse window end"	6,0		%Vmax		
	Pulse backwards	20,0		%Vmax		
	Facing to the limit stop	10,0		%Vmax		
	Facing jog	28,0		%Vmax		
73	Speed reduction in automatic mode					
	Clamp closed	20		%Vmax		
	Open collet	30		%Vmax		
77	Torque reduction in manual mode	##		%Cmax		
	Forwards slowly	40		%Cmax		
	Forwards fast	70		%Cmax		
	Backwards slowly	70		%Cmax		
	Backwards fast	70		%Cmax		
78	Torque reduction during bar change	##		%Cmax		
	From "collet entry slowdown" to "pulse window end"	40		%Cmax		
	Pulse backwards	100		%Cmax		
	Facing to the limit stop	35		%Cmax		
	Facing jog	50		%Cmax		
79	Torque reduction in automatic mode	##		%Cmax		
	Clamp closed	10		%Cmax		
	Open collet	40		%Cmax		



KID 80 SIV

PARAMETER LIST FOR THE AXIS FUNCTIONS					
Par. No.	Parameter description	Default value	Allocated value	Unit of	
		KID IV		measureme nt	
84	Keyboard on the opposite side	0			



F PARAMETER LIST FOR THE INTERFACE

Customer	Date
Bar feeder model	S/N

PARAMETER LIST FOR THE INTERFACE					
Par No	Parameter description		Default value		Unit of
r anno.			KID IV	value	measureme
85	Interface signals				IIL
	Bar change	(0=NO/1=NC)	0		
	Feeding	(0=NO/1=NC)	0		
	Man. feeding	(0=NO/1=NC)	0		
	Man. return	(0=NO/1=NC)	0		
	Man/aut from lathe	(0=NO/1=NC)	0		
	Feeding cycle	(0=NO/1=NC)	0		
	Feeding stop	(0=NO/1=NC)	0 (0)		
	Door safety devices (0=NO/1=NC)		1		
	Threading safety device (0=NO/1=NC)	9	0		
	Start from lathe	(0=NO/1=NC)	0		
	Safety devices from lat (0=NO/1=NC)	he	1		
	Sturtup	(0=NO/1=NC)	0		
	Working mode	(0=NO/1=NC)	0		



KID 80 SIV

G GENERAL PARAMETER LIST

Customer	Date
Bar feeder model	S/N

GENERAL PARAMETER LIST					
Par.No.	Parameter description	Default value KID IV	Allocated value	Unit of measure ment	
89	Fair Demo 0= turned off 1= turned on	0			
90	Wrong bar feeder phase 0= K37 active with closed guide channels in manual mode 1= Bar feeder in manual mode and lathe in automatic mode	0			
98	Indicators (only on touch)	/			
99	SMS service (only on touch)	/			
100	E-MAIL service (only on touch)	/			